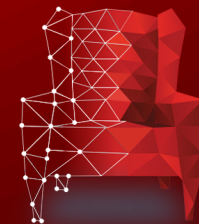


# How To Teach ROS

Ricardo Téllez,  
ROS teacher at  
La Salle University, Barcelona

November, 2019



The  
Construct

For ROS Developers

**Based on my experience**

**The only way to make  
students learn ROS is by  
making them practice**

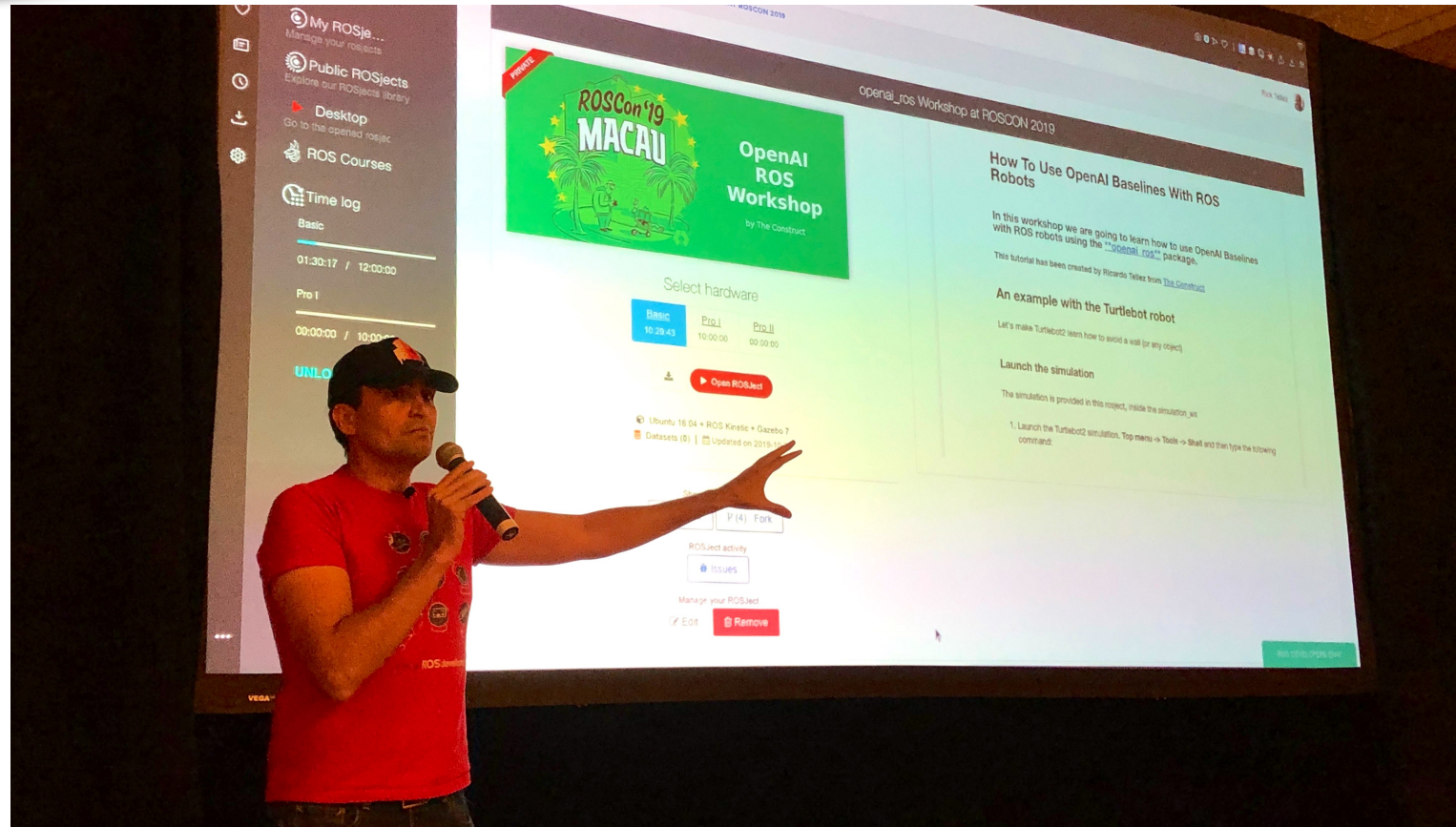
**... a lot!**





## **Today You Will Learn**

**A method for teaching ROS based on practice, without all the problems associated to making students practice ROS**



**Ricardo Téllez, ROS Teacher at La Salle University**  
Teaching OpenAI with ROS at **ROSCON 2019**, using this method

(Watch the full webinar here: <https://youtu.be/gtBzAH-jeM0>)





**Ricardo Téllez, ROS Teacher at La Salle University**

Teaching ROS at **Master of Robotics** at La Salle University, Barcelona 2019



**Ricardo Téllez, ROS Teacher at La Salle University**

Teaching **ROS** online every Tuesday at 18:00 CET since 2017

Free attendance here: <https://bit.ly/2DxctVl>

# If you are looking for

- **A fast method to create a ROS course based on slides...**
  - Just search over internet and get one of the trillions available
    - for example, this one by ETH Zurich: <https://bit.ly/35OqmLV>
  - Change the logo in the slides by your logo.
  - Done.
- **Want it even easier?**
  - Point the students to the ROS Wiki and tell them to study by themselves: [wiki.ros.org](http://wiki.ros.org)
  - Done.





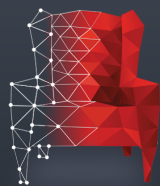
**This webinar is not for selling you anything**

I'm going to provide you with real practical stuff for your teaching:  
a method, a structure, code, simulations and documentation...

**all for free**



# Problems Teaching ROS



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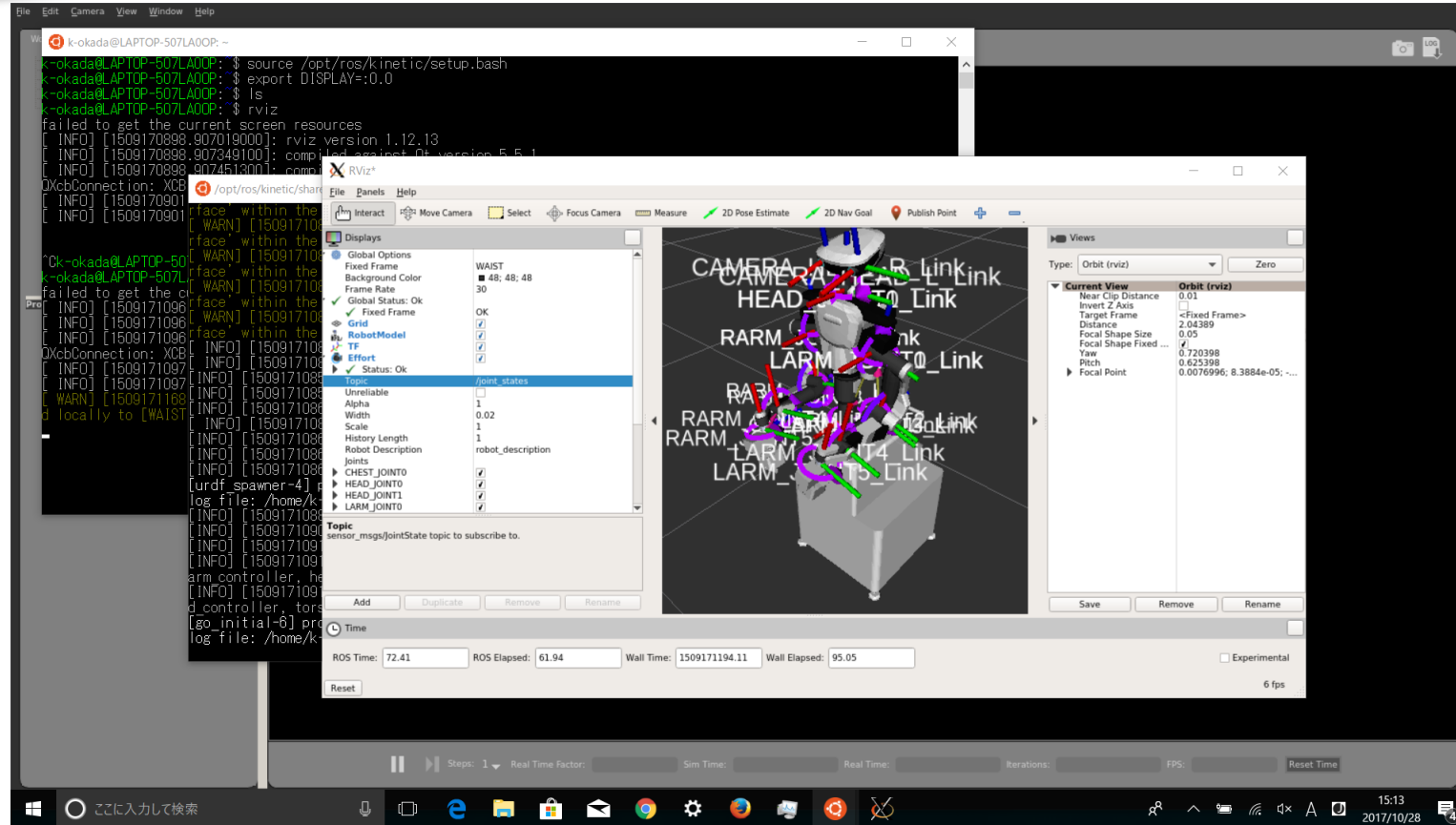
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For ROS Developers



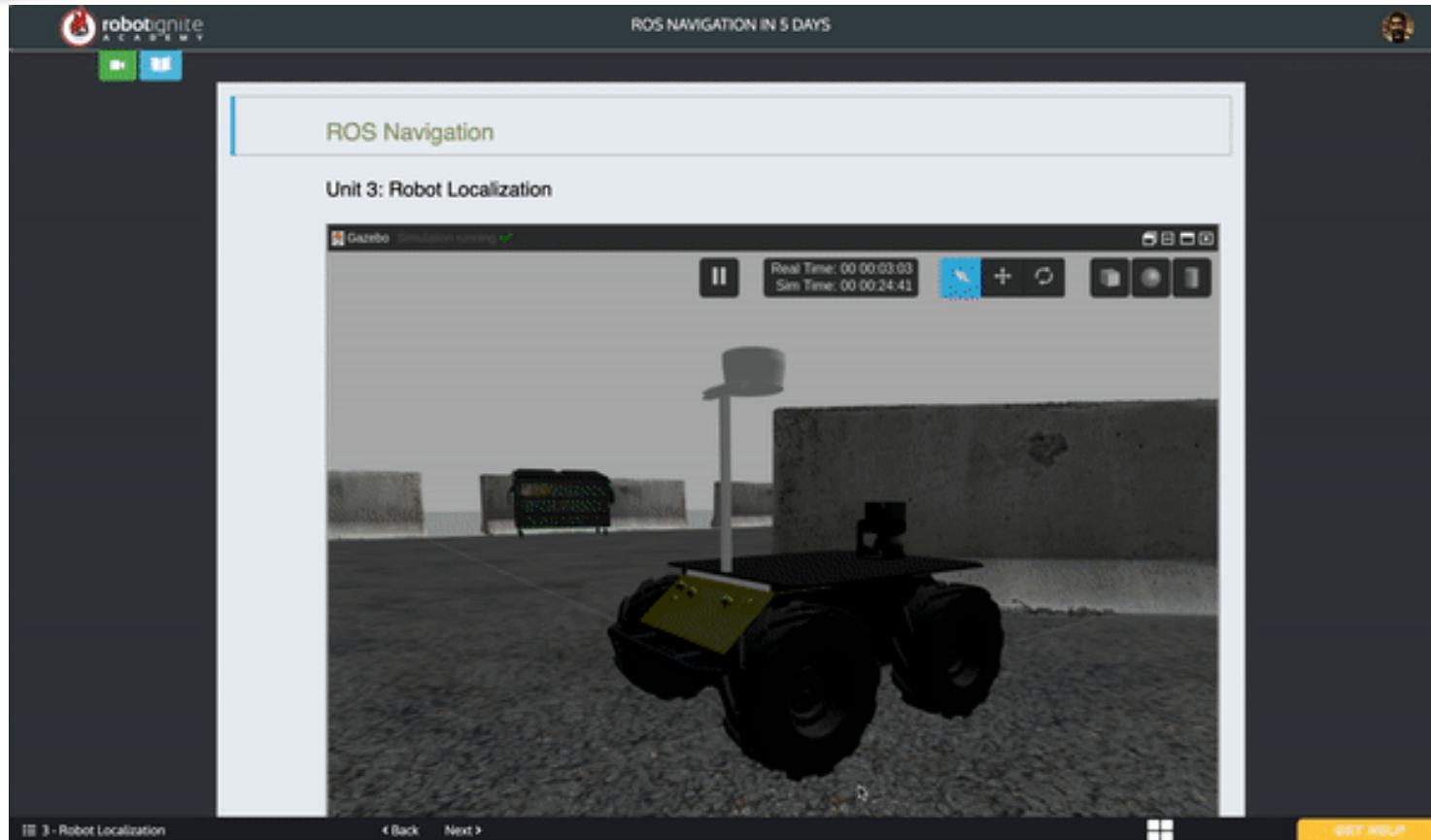
### Problem #1

Students don't know about Linux nor Python/C++



## Problem #2

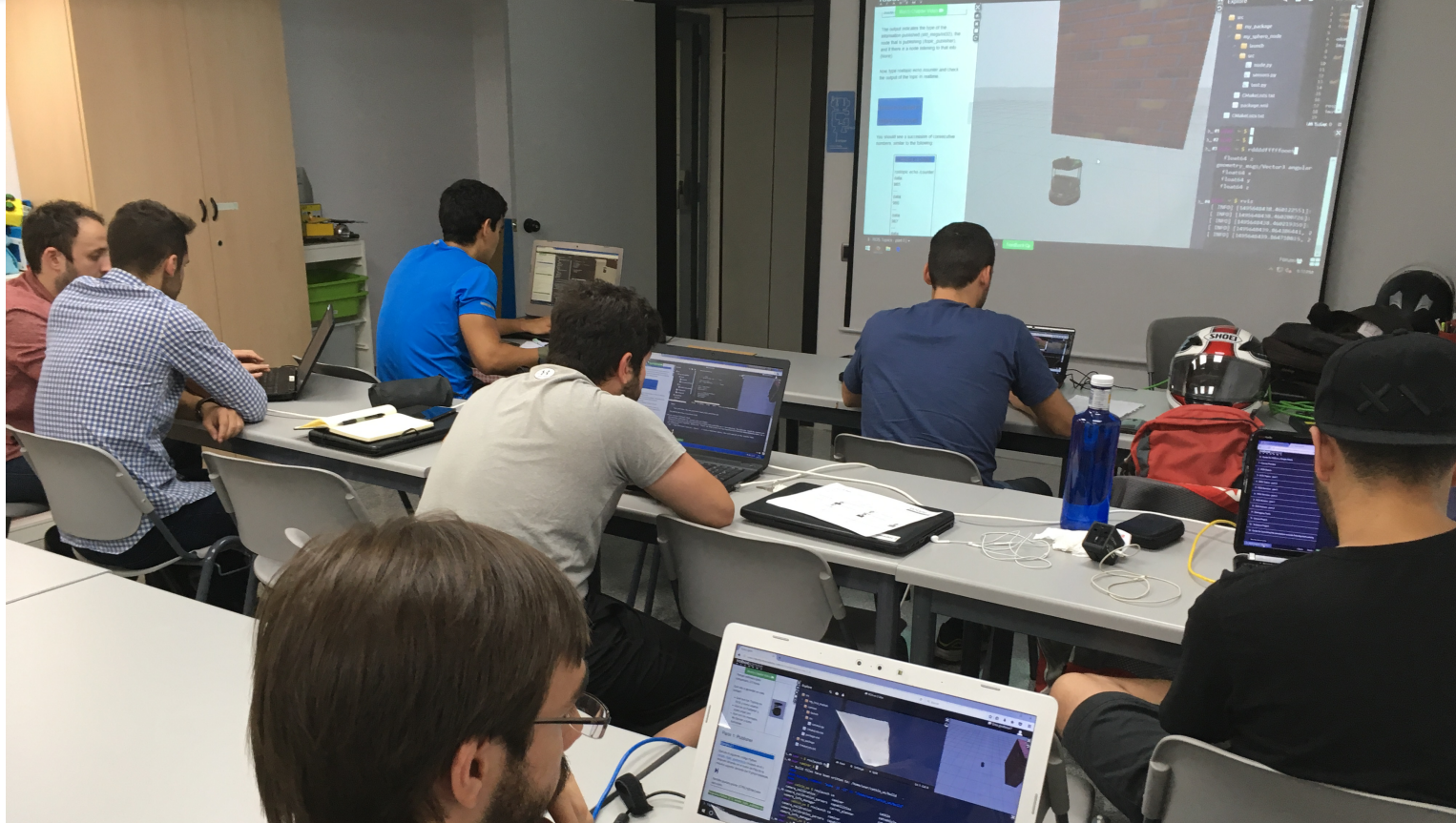
Installing ROS in students' computers is difficult  
(mostly Windows computers)



### Problem #3

Preparing the curriculum is a hard work

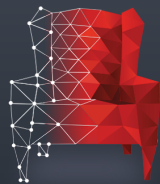




## Problem #4

### Making students practice is difficult

# How To Teach ROS

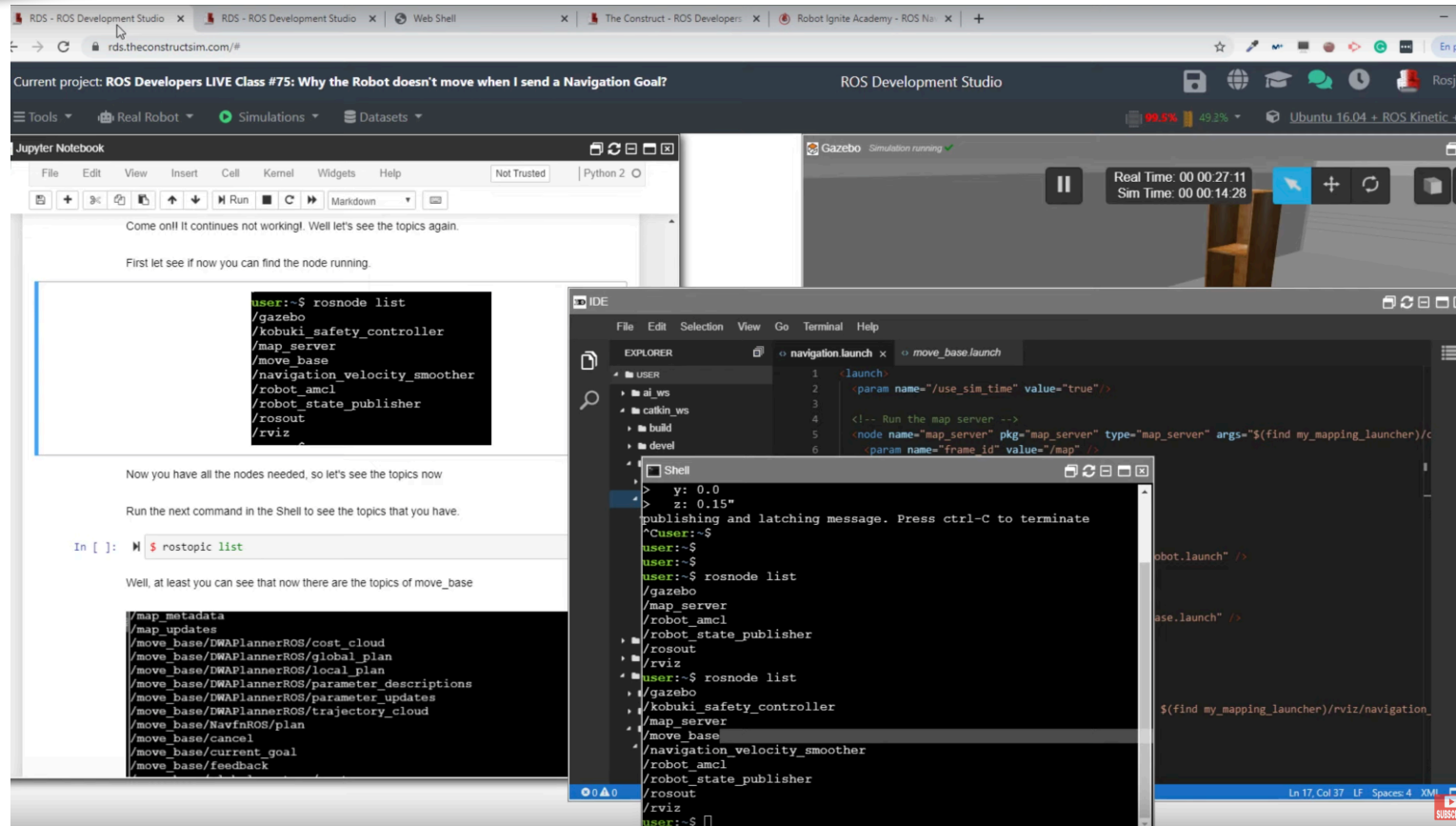


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For ROS Developers





ROS Development Studio <http://rosds.online>

A full ROS cloud environment in your browser

Create a free account

# Decide Teaching Setup

- Decide which **robotics subject** to teach
- Decide which **ROS Distribution** to use
- Decide **programming language** to use
  
- Subject: **Robot Navigation**
- ROS Distribution: **ROS2 Eloquent**
- Programming language: **Python**





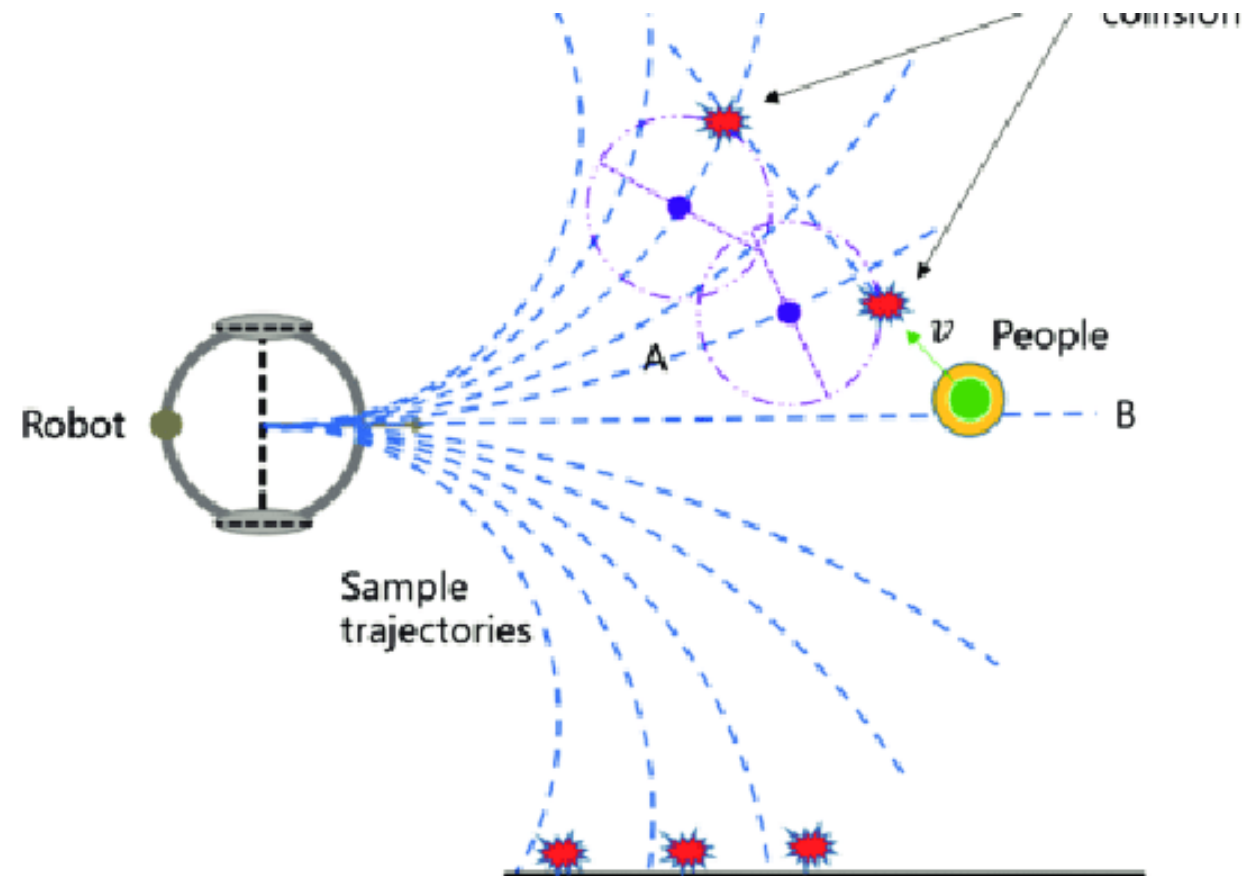
# Pre-Requisites

- Make students learn the requisites:
  - Learn Linux
  - Learn Python
- Make them take these online free courses:
- **Linux for robotics:** <https://tinyurl.com/yxuo5urh>
- **Python for robotics:** <https://tinyurl.com/y2en8pl8>
- Already filtered for you all the knowledge into the useful bites for robotics
- Take the exam and get evaluation for you.



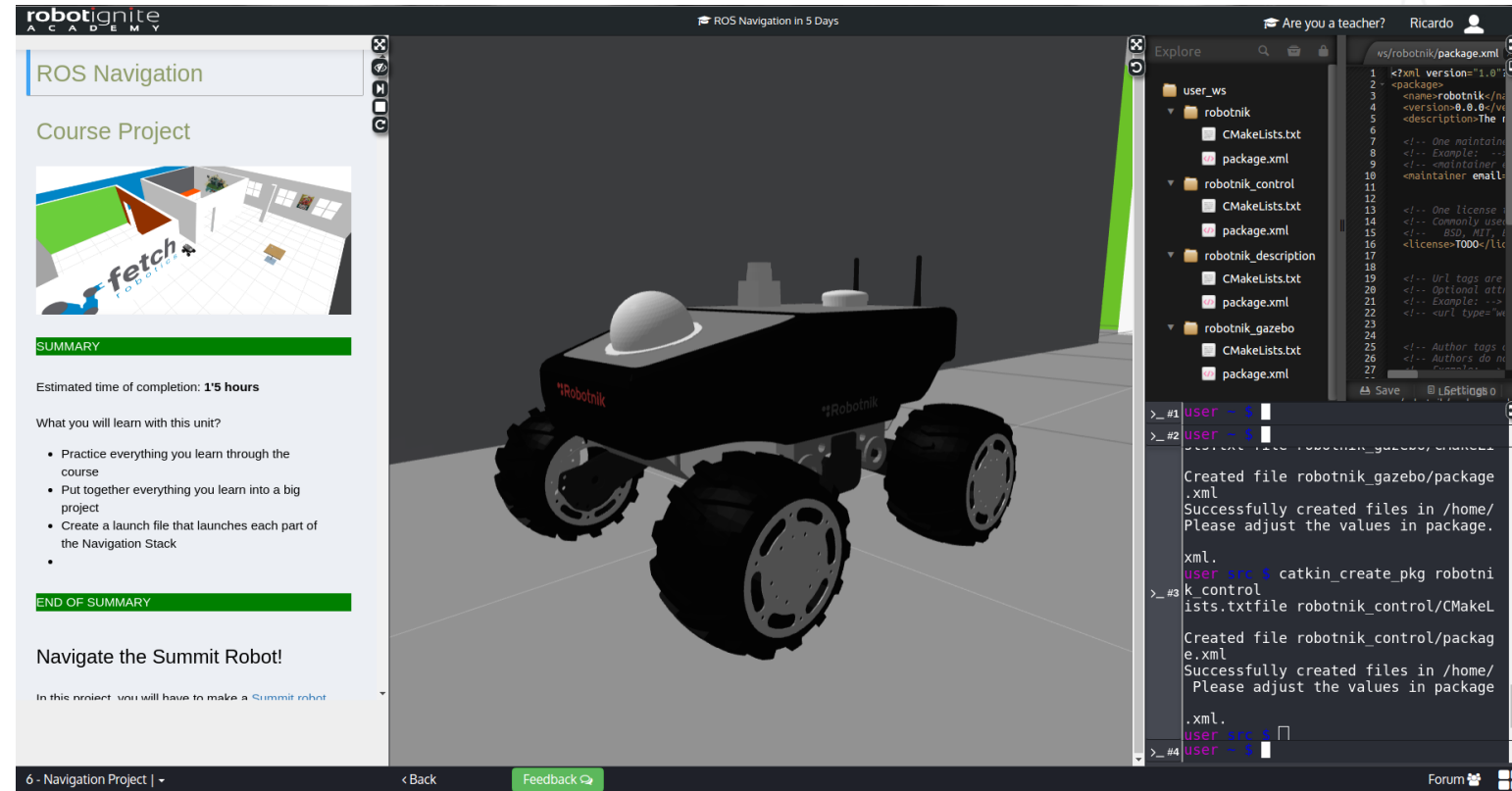
# Decide Units of Course

- Unit 1: Odometry based navigation
- Unit 2: Sensors for robot navigation
- Unit 3: SLAM Map Building
- Unit 4: Monte Carlo Localisation
- Unit 5: Rapid Random Trees Path Planning
- Unit 6: Dynamic Window Approach
- Project: Patrol Control



# Decide Robots To Use

- Unit 1: **Summit XL** by Robotnik
- Unit 2: **Husky** by Clearpath
- Unit 3: **Turtlebot 2** by Yujin
- Unit 4: **Velocity** by Botnuvo
- Unit 5: **ROSBot** by Husarion
- Unit 6: **RB-1** by Robotnik
- Project: **Turtlebot 2** by Yujin



**For Each Unit Do**



# Create a ROSject

- **ROSject** means **ROS** project
- It will contain all the **teaching material for each Unit**

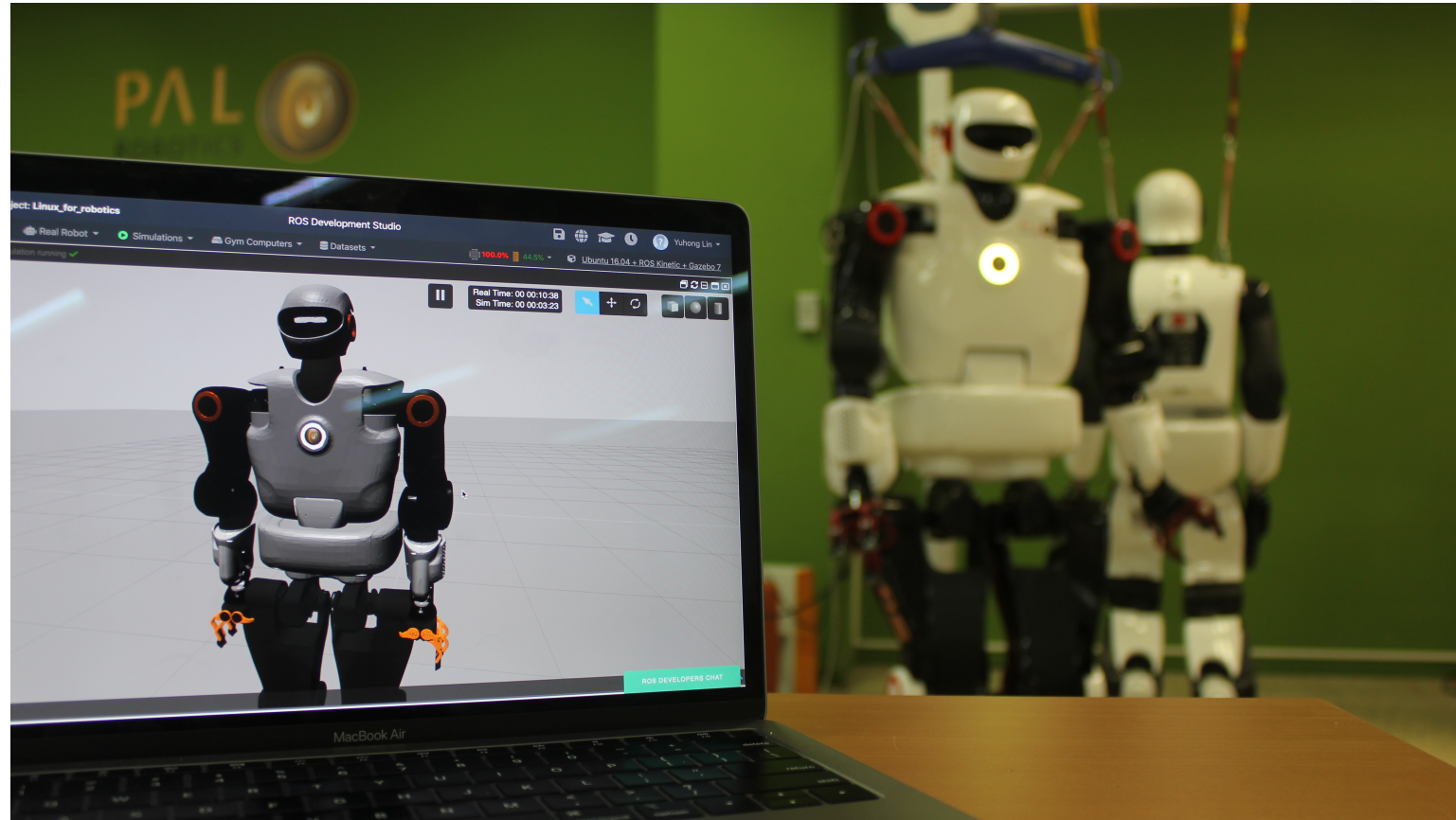
The screenshot displays the ROS Development Studio environment. On the left, a 3D model of a differential-drive robot is shown in a simulated environment. The top bar indicates the current project is 'turtlebot3' and shows various tool icons. The main workspace is divided into three panels:

- Code Editor:** Displays a Python script named 'basic.py' in the 'catkin\_ws/src' directory. The script includes imports for 'rospy', 'nav\_msgs', and 'geometry\_msgs', and defines an 'odomCallback' function that publishes a 'Twist' message.
- File Explorer:** Shows the directory structure of the workspace, including 'catkin\_ws', 'build', 'devel', and 'src'.
- Jupyter Notebook:** Contains a code cell defining the structure of a 'Twist' message using 'geometry\_msgs/Vector3' for linear and angular velocities.

The Jupyter Notebook output shows the structure of the 'Twist' message, which consists of two 'Vector3' objects: one for linear velocity (x, y, z) and one for angular velocity (x, y, z).

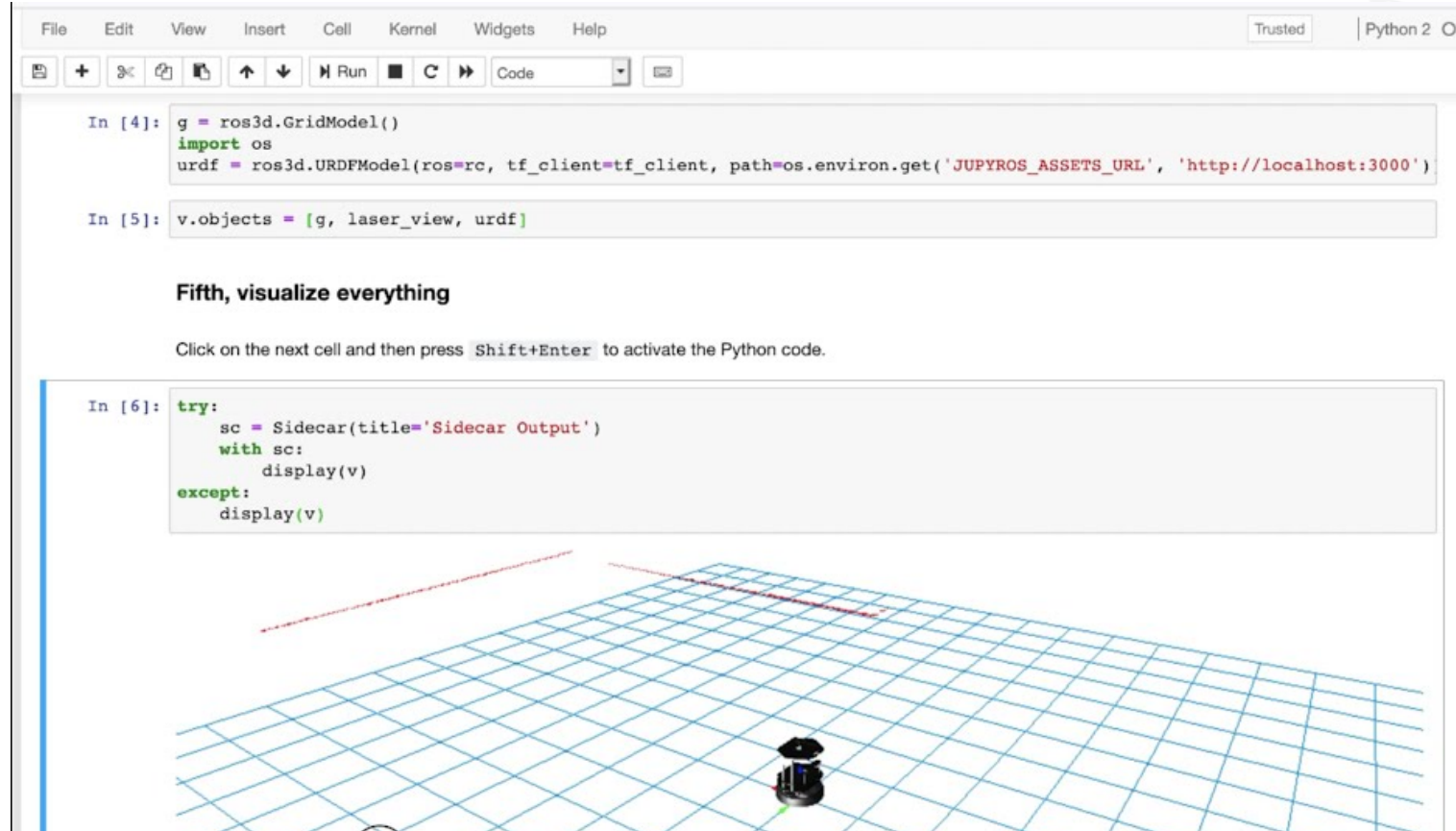
# Get the simulation

- Need to use robot simulations to practice
- Get simulations from repos or included in ROSDS
- **The Construct open source simulations repo** (for Kinetic or Melodic):
  - <https://bit.ly/2Gp601m>



# Create Unit Text

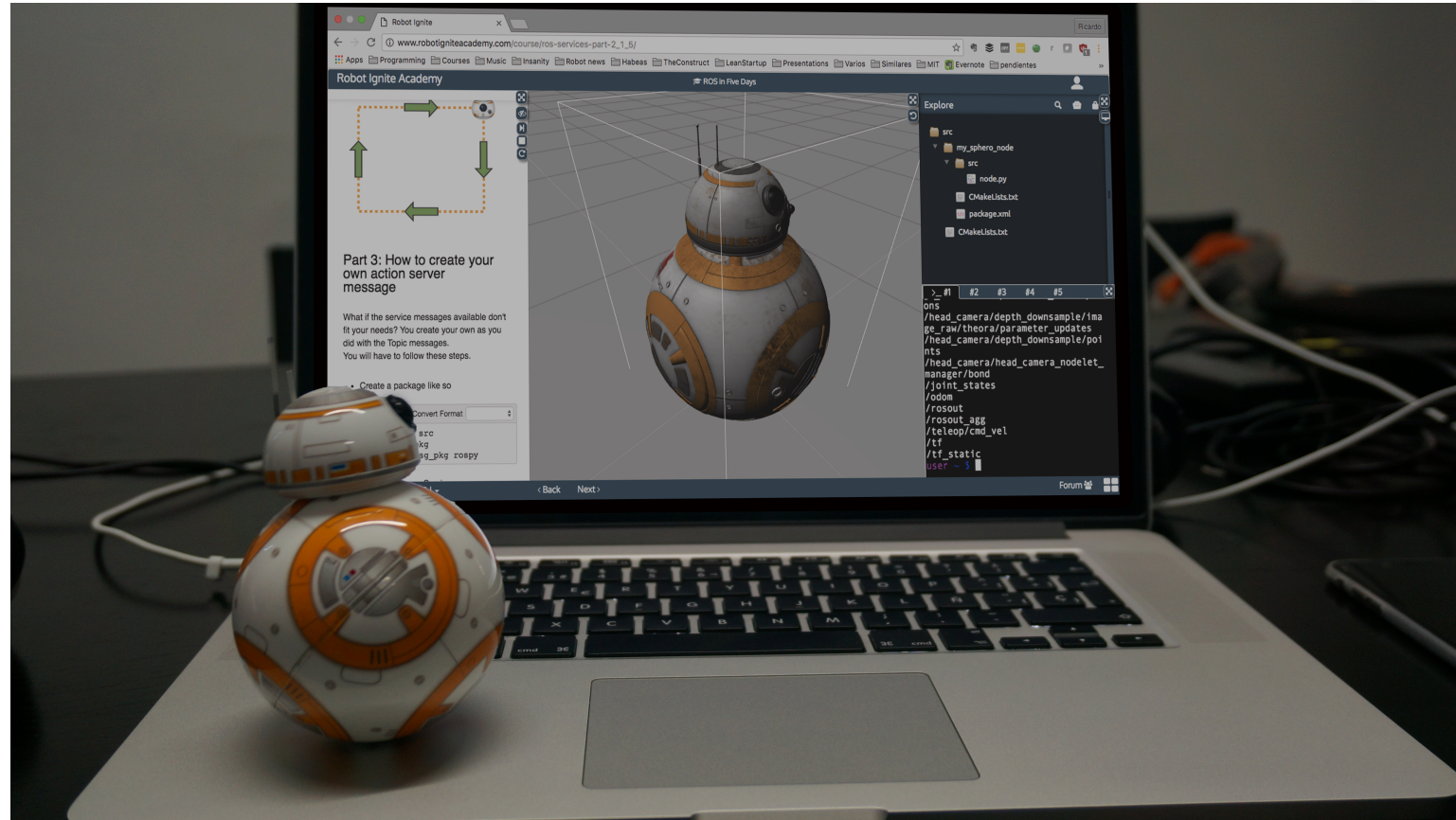
- Use Jupiter Notebooks
- Include text explanations
- Embed videos and pictures
- Embed Python code
- Interact with the robot directly from the notebook





# Provide Sample Code

- Add some code to the Unit so the student can use or modify.
- You can provide it **as a template**



**Repeat For Each Unit**

# Add Final Project

- Create an additional ROSject
- The project must contain an exercise that includes all the units knowledge
- Include if possible connection with real robot





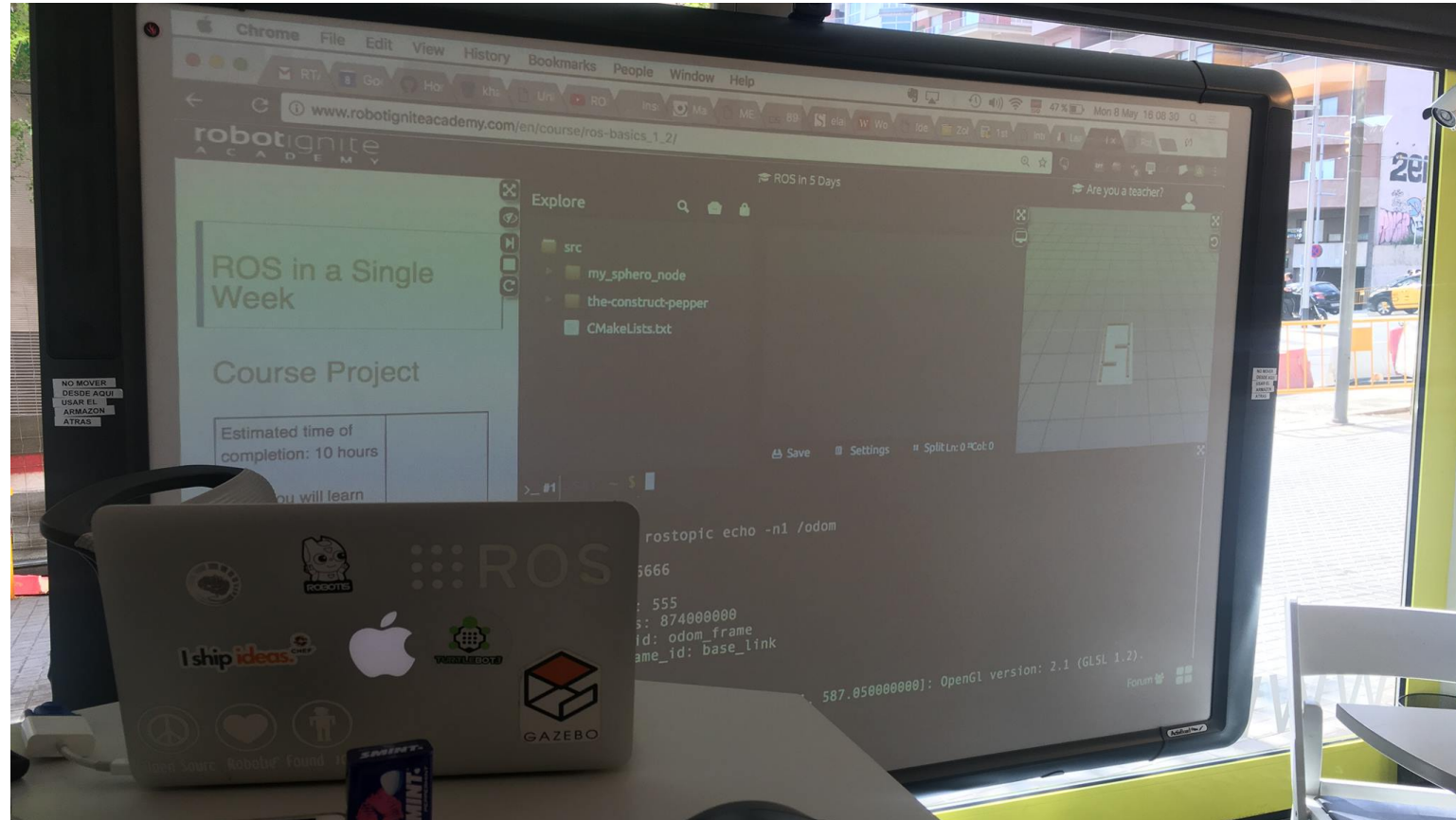
# Add An Exam!

- EXAM IS SUPER IMPORTANT!!!
- Not only to evaluate, but also to make them learn
- Create additional ROSject with it



# Share With Students

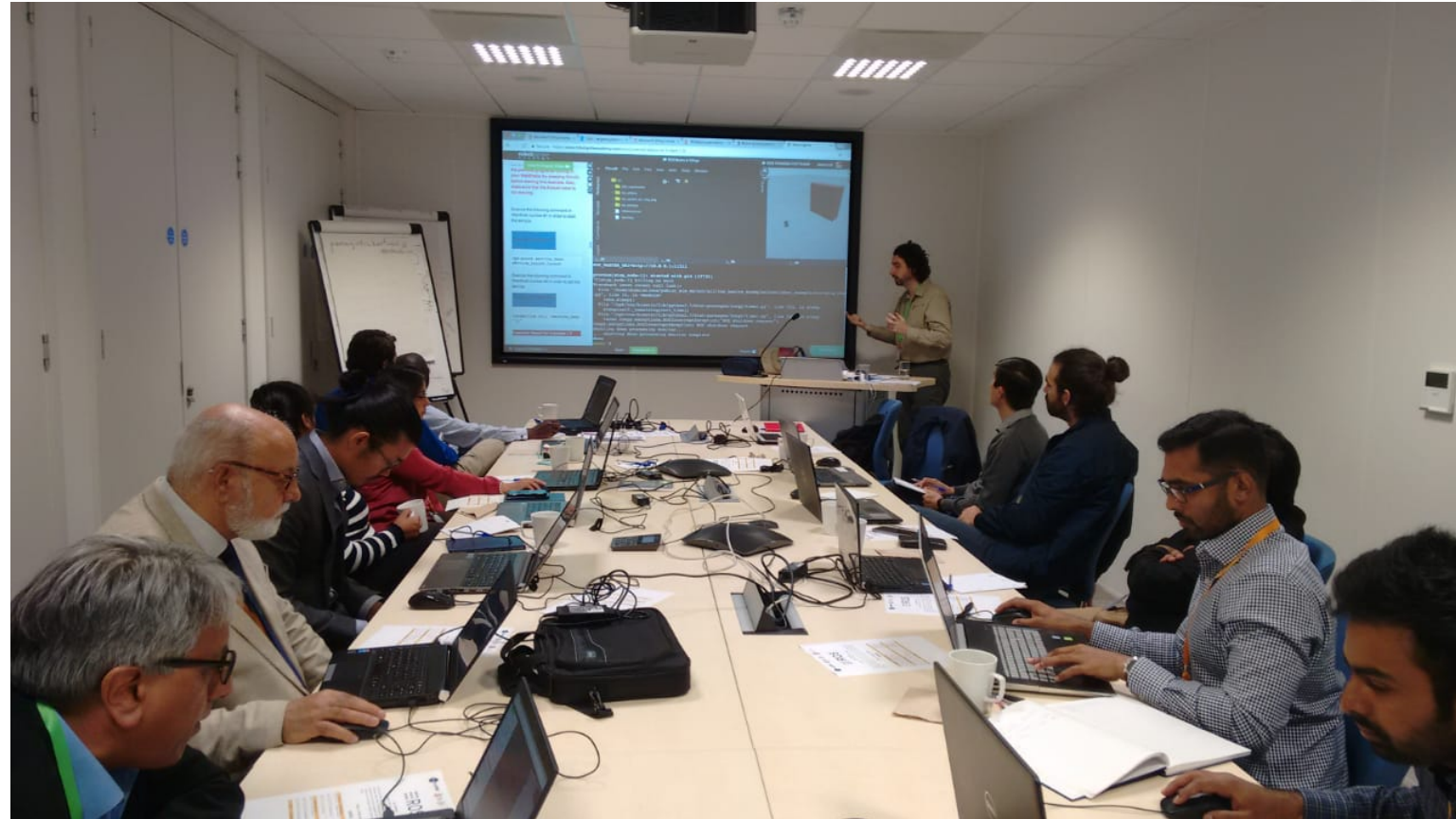
- Generate the rosject link and share with the students





# Enjoy Teaching!

- Use the ROSject docs as a guide for you
- Make students practice with you while you are explaining
- Make them do exercises
- Support your students with their questions



# Summary Of The Process

## 1. Decide:

- Subject to teach
- Units of the course
- Programming language.

## 2. Create a rosject for each unit

## 3. Get a robot simulation for each unit

## 4. Create a Jupyter notebook for each unit

## 5. Create some sample code

## 6. Repeat for each unit, project and exam

## 7. Share with students



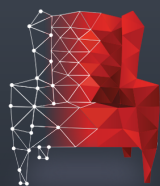


# ROSject Examples

- **Unit 1:** <http://www.rosject.io/l/b5c1af3/>
- **Project:** <https://bit.ly/2K1RCNq>
- **Exam:** <http://www.rosject.io/l/b5e14b5/>



# We Have An All Set Solution



The  
Construct

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For ROS Developers

# Advantages of our solution

- All students set in 1 minute after you start first class
  - No matter which computer they use
  - Get a control of the students work
  - Get all the material done ready to teach
  - Get exams and correction of them
  - Provide LinkedIn certificate
- 
- Enjoy yourself to teach instead of wasting your time with the preparation

# Some Universities Using Our Solution



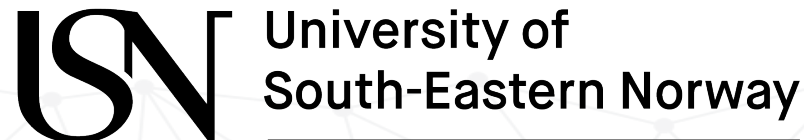
AALBORG UNIVERSITET



THE UNIVERSITY OF SYDNEY

laSalle

RAMON LLULL UNIVERSITY







“With The Construct our students can jump right into ROS without all the hardware and software setup problems. And the best: they can do this from everywhere”

Steffen Pfiffner

Lecturer at University of Weingarten



## BONUS: **FREE 30 MIN CONSULTANCY**

Questions about ROS & Teaching?  
Book a consultancy with me and learn how you can  
implement the teaching method at your own universities.

Schedule it here:

<https://app.hubspot.com/meetings/rtellez1>

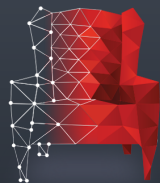
# Contact

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[www.theconstruct.ai](http://www.theconstruct.ai)



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